

# calculus of variations

calculus of variations is a fascinating branch of mathematical analysis that deals with the optimization of functionals, which are mappings from a set of functions to real numbers. It has significant applications in various fields including physics, engineering, and economics. The principles of calculus of variations are used to find the function that minimizes or maximizes a given functional, leading to the solution of complex problems. In this article, we will delve into the fundamental concepts of calculus of variations, its historical development, key principles and techniques, applications, and some notable problems that exemplify its utility. By the end of this article, you will have a comprehensive understanding of this essential area of mathematics.

- Introduction to Calculus of Variations
- Historical Background
- Fundamental Concepts
- Key Principles and Techniques
- Applications of Calculus of Variations
- Notable Problems in Calculus of Variations
- Conclusion

# Introduction to Calculus of Variations

Calculus of variations is primarily concerned with finding the extrema of functionals, which are often represented as integrals. A functional takes a function as input and produces a scalar output. The classical problems in calculus of variations include determining the shortest path, the shape of a hanging cable, and the optimal control of dynamical systems. The study of this field involves the use of differential equations, optimization techniques, and the Euler-Lagrange equation, which is fundamental to deriving optimal solutions.

The methods used in calculus of variations can be quite complex and require a solid understanding of both calculus and differential equations. However, the results obtained are immensely powerful and applicable to a wide range of scientific inquiries. This section lays the groundwork for understanding the historical context, fundamental concepts, and methodologies that follow.

## Historical Background

The roots of calculus of variations can be traced back to the early 18th century, with notable contributions from mathematicians such as Leonhard Euler and Joseph-Louis Lagrange.

### The Contributions of Euler

Leonhard Euler is often credited as the founder of the calculus of variations. In his work, he introduced the concept of functionals and formulated the first variational problems. One of his significant contributions was the formulation of the Euler-Lagrange equation, which provides a necessary condition for a function to be an extremum of a functional.

### The Influence of Lagrange

Joseph-Louis Lagrange further developed the field by applying variational principles to mechanics, leading to what is now known as Lagrangian mechanics. This framework allowed for the formulation of

the equations of motion for a system in terms of energy rather than forces, establishing a profound connection between physics and mathematics.

## Fundamental Concepts

To grasp the essence of calculus of variations, it is crucial to understand its fundamental concepts, including functionals, variations, and the Euler-Lagrange equation.

### Functionals

A functional can be defined as a mapping from a space of functions into the real numbers. Mathematically, it is denoted as  $J[y(x)]$ , where  $y(x)$  is a function from a specified space. A common example of a functional is given by:

$$J[y] = \int F(y, y', x) dx$$

where  $F$  is a function of  $y$ , its derivative  $y'$ , and the independent variable  $x$ .

### Variations

The concept of variation is central to the calculus of variations. A variation  $\delta y$  of a function  $y(x)$  is a small change in the function. The goal is to determine how these variations affect the value of the functional  $J$ . The first variation  $\delta J$  of a functional can be expressed as:

$$\delta J = J[y + \delta y] - J[y]$$

### The Euler-Lagrange Equation

The Euler-Lagrange equation is derived from the principle of stationary action, which states that the

true path taken by a system is the one for which the action functional is stationary (i.e., has a local minimum or maximum). The equation is given by:

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left( \frac{\partial F}{\partial y'} \right) = 0$$

This equation must be satisfied by any function  $y(x)$  that extremizes the functional  $J[y]$ .

## Key Principles and Techniques

Several techniques are employed in calculus of variations to solve problems effectively. Understanding these principles is essential for applying the methods to real-world scenarios.

### Direct Methods

Direct methods involve finding extremal functions by solving the Euler-Lagrange equation directly. This method is straightforward but can be quite challenging depending on the complexity of the functional.

### Indirect Methods

Indirect methods often utilize the concept of perturbation to study how small changes in a function affect the functional. These methods can provide insights where direct methods may fail.

## Boundary Conditions

Boundary conditions play a crucial role in variational problems. They specify the values or behaviors of the function at the endpoints of the interval over which the functional is defined. Types of boundary conditions include fixed endpoints, free endpoints, and mixed conditions.

- Fixed Endpoints: The function values are specified at the boundaries.

- Free Endpoints: The function values are not specified, allowing for more flexibility.
- Mixed Conditions: A combination of fixed and free conditions is applied.

## Applications of Calculus of Variations

The applications of calculus of variations are vast and impactful across multiple disciplines. Some prominent areas include:

### Physics

In physics, calculus of variations is used to derive the equations of motion in classical mechanics. The principles underpinning Lagrangian mechanics are fundamentally rooted in variational methods.

### Engineering

Engineers apply calculus of variations in structural optimization, optimal control, and design problems. For instance, the design of beams and trusses often utilizes variational principles to minimize material usage while maintaining structural integrity.

### Economics

In economics, calculus of variations can be used in optimizing resource allocation over time, particularly in dynamic programming and control theory.

# Notable Problems in Calculus of Variations

Several classic problems illustrate the principles of calculus of variations. Understanding these problems provides insight into the application of the theory.

## The Brachistochrone Problem

The brachistochrone problem asks for the shape of a wire down which a bead will slide from one point to another in the least time. The solution is a cycloid, which can be derived using the calculus of variations.

## The Catenary Problem

The catenary problem involves finding the shape of a hanging chain or cable under its own weight. The resulting curve, known as a catenary, can also be found using variational methods.

## Conclusion

Calculus of variations stands as a pivotal branch of mathematics with extensive applications across various fields. Its powerful principles, particularly the Euler-Lagrange equation, enable scientists and engineers to solve complex optimization problems efficiently. Understanding the historical context, fundamental concepts, and key techniques of this discipline is essential for anyone looking to apply mathematical optimization in real-world scenarios. As research continues to evolve, the relevance and applications of calculus of variations are expected to grow, further enriching our understanding of complex systems.

## Q: What is calculus of variations used for?

A: Calculus of variations is used to find the function that minimizes or maximizes a functional, which has applications in physics, engineering, economics, and various optimization problems.

## **Q: Who are the key figures in the history of calculus of variations?**

A: Key figures include Leonhard Euler, who formulated the Euler-Lagrange equation, and Joseph-Louis Lagrange, who applied variational principles to mechanics, establishing a connection between mathematics and physics.

## **Q: What is the Euler-Lagrange equation?**

A: The Euler-Lagrange equation is a fundamental equation in calculus of variations that provides necessary conditions for a function to be an extremum of a functional. It is given by  $\frac{\partial F}{\partial y} - \frac{d}{dx}(\frac{\partial F}{\partial y'}) = 0$ .

## **Q: Can calculus of variations solve real-world problems?**

A: Yes, calculus of variations can solve real-world problems in various fields such as optimizing the design of structures, determining the shortest paths, and analyzing dynamic systems in economics.

## **Q: What are some classic problems in calculus of variations?**

A: Classic problems include the brachistochrone problem, which seeks the quickest descent path between two points, and the catenary problem, which finds the shape of a hanging cable.

## **Q: How does one apply direct methods in calculus of variations?**

A: Direct methods involve solving the Euler-Lagrange equation directly to find extremal functions, often requiring knowledge of calculus and differential equations.

## **Q: What role do boundary conditions play in calculus of variations?**

A: Boundary conditions specify the values or behaviors of the function at the limits of the interval over

which the functional is defined, affecting the solution to variational problems.

### Q: What is the significance of variations in this field?

A: Variations represent small changes in functions, and analyzing how these changes affect the functional is crucial for determining optimal solutions in calculus of variations.

### Q: How is calculus of variations related to optimization?

A: Calculus of variations is fundamentally about optimization; it seeks to find the best function that minimizes or maximizes a given functional, making it a key tool in optimization theory.

### Q: Is calculus of variations applicable in modern technology?

A: Yes, calculus of variations is widely used in modern technology, particularly in fields like robotics, aerospace engineering, and financial modeling, where optimization plays a critical role.

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**calculus of variations:** Calculus of Variations I Mariano Giaquinta, Stefan Hildebrandt, 2004-06-23 This two-volume treatise is a standard reference in the field. It pays special attention to the historical aspects and the origins partly in applied problems—such as those of geometric optics—of parts of the theory. It contains an introduction to each chapter, section, and subsection and an overview of the relevant literature in the footnotes and bibliography. It also includes an index of the examples used throughout the book.

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optimal control theory. The author opens with the study of three classical problems whose solutions led to the theory of calculus of variations. They are the problem of geodesics, the brachistochrone, and the minimal surface of revolution. He gives a detailed discussion of the Hamilton-Jacobi theory, both in the parametric and nonparametric forms. This leads to the development of sufficiency theories describing properties of minimizing extremal arcs. Next, the author addresses existence theorems. He first develops Hilbert's basic existence theorem for parametric problems and studies some of its consequences. Finally, he develops the theory of generalized curves and automatic existence theorems. In the second part of the book, the author discusses optimal control problems. He notes that originally these problems were formulated as problems of Lagrange and Mayer in terms of differential constraints. In the control formulation, these constraints are expressed in a more convenient form in terms of control functions. After pointing out the new phenomenon that may arise, namely, the lack of controllability, the author develops the maximum principle and illustrates this principle by standard examples that show the switching phenomena that may occur. He extends the theory of geodesic coverings to optimal control problems. Finally, he extends the problem to generalized optimal control problems and obtains the corresponding existence theorems.

**calculus of variations: A History of the Calculus of Variations from the 17th through the 19th Century** H. H. Goldstine, 2012-12-06 The calculus of variations is a subject whose beginning can be precisely dated. It might be said to begin at the moment that Euler coined the name calculus of variations but this is, of course, not the true moment of inception of the subject. It would not have been unreasonable if I had gone back to the set of isoperimetric problems considered by Greek mathematicians such as Zenodorus (c. 200 B. C. ) and preserved by Pappus (c. 300 A. D. ). I have not done this since these problems were solved by geometric means. Instead I have arbitrarily chosen to begin with Fermat's elegant principle of least time. He used this principle in 1662 to show how a light ray was refracted at the interface between two optical media of different densities. This analysis of Fermat seems to me especially appropriate as a starting point: He used the methods of the calculus to minimize the time of passage of a light ray through the two media, and his method was adapted by John Bernoulli to solve the brachistochrone problem. There have been several other histories of the subject, but they are now hopelessly archaic. One by Robert Woodhouse appeared in 1810 and another by Isaac Todhunter in 1861.

**calculus of variations: Direct Methods in the Calculus of Variations** Enrico Giusti, 2003 This book provides a comprehensive discussion on the existence and regularity of minima of regular integrals in the calculus of variations and of solutions to elliptic partial differential equations and systems of the second order. While direct methods for the existence of solutions are well known and have been widely used in the last century, the regularity of the minima was always obtained by means of the Euler equation as a part of the general theory of partial differential equations. In this book, using the notion of the quasi-minimum introduced by Giaquinta and the author, the direct methods are extended to the regularity of the minima of functionals in the calculus of variations, and of solutions to partial differential equations. This unified treatment offers a substantial economy in the assumptions, and permits a deeper understanding of the nature of the regularity and singularities of the solutions. The book is essentially self-contained, and requires only a general knowledge of the elements of Lebesgue integration theory. Contents: Semi-Classical Theory; Measurable Functions; Sobolev Spaces; Convexity and Semicontinuity; Quasi-Convex Functionals; Quasi-Minima; Hölder Continuity; First Derivatives; Partial Regularity; Higher Derivatives. Readership: Graduate students, academics and researchers in the field of analysis and differential equations.

**calculus of variations: The Calculus of Variations and Optimal Control** George Leitmann, 1981-05-31 This book is intended to present an introductory treatment of the calculus of variations in Part I and of optimal control theory in Part II. The discussion in Part I is restricted to the simplest problem of the calculus of variations. The topic is entirely classical; all of the basic theory had been developed before the turn of the century. Consequently the material comes from many sources.

**calculus of variations: The Inverse Problem of the Calculus of Variations** Dmitry V. Zenkov,

2015-10-15 The aim of the present book is to give a systematic treatment of the inverse problem of the calculus of variations, i.e. how to recognize whether a system of differential equations can be treated as a system for extremals of a variational functional (the Euler-Lagrange equations), using contemporary geometric methods. Selected applications in geometry, physics, optimal control, and general relativity are also considered. The book includes the following chapters: - Helmholtz conditions and the method of controlled Lagrangians (Bloch, Krupka, Zenkov) - The Sonin-Douglas's problem (Krupka) - Inverse variational problem and symmetry in action: The Ostrogradskyj relativistic third order dynamics (Matsyuk.) - Source forms and their variational completion (Voicu) - First-order variational sequences and the inverse problem of the calculus of variations (Urban, Volna) - The inverse problem of the calculus of variations on Grassmann fibrations (Urban).

**calculus of variations:** Translations of Mathematical Monographs , 1962

**calculus of variations:** The Calculus of Variations in the Large Marston Morse, 1934-12-31 Morse theory is a study of deep connections between analysis and topology. In its classical form, it provides a relationship between the critical points of certain smooth functions on a manifold and the topology of the manifold. It has been used by geometers, topologists, physicists, and others as a remarkably effective tool to study manifolds. In the 1980s and 1990s, Morse theory was extended to infinite dimensions with great success. This book is Morse's own exposition of his ideas. It has been called one of the most important and influential mathematical works of the twentieth century. Calculus of Variations in the Large is certainly one of the essential references on Morse theory.

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Brechtken-Mandersch, 1991-06-01 This text provides a clear, concise introduction to the calculus of variations. The introductory chapter provides a general sense of the subject through a discussion of several classical and contemporary examples of the subject's use.

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**calculus of variations:** *Selected Chapters in the Calculus of Variations* Jürgen Moser, 2003-05-23 0.1 Introduction These lecture notes describe a new development in the calculus of variations which is called Aubry-Mather-Theory. The starting point for the theoretical physicist Aubry was a model for the description of the motion of electrons in a two-dimensional crystal. Aubry investigated a related discrete variational problem and the corresponding minimal solutions. On the other hand, Mather started with a specific class of area-preserving annulus mappings, the so-called monotone twist maps. These maps appear in mechanics as Poincaré maps. Such maps were studied by Birkhoff during the 1920s in several papers. In 1982, Mather succeeded to make essential progress in this field and to prove the existence of a class of closed invariant subsets which are now called Mather sets. His existence theorem is based again on a variational principle. Although these two investigations have different motivations, they are closely related and have the same mathematical foundation. We will not follow those approaches but will make a connection to classical results of Jacobi, Legendre, Weierstrass and others from the 19th century. Therefore in

Chapter I, we will put together the results of the classical theory which are the most important for us. The notion of extremal fields will be most relevant. In Chapter II we will investigate variational problems on the 2-dimensional torus. We will look at the corresponding global minimals as well as at the relation between minimals and extremal fields. In this way, we will be led to Mather sets.

**calculus of variations: The Inverse Problem of the Calculus of Variations for Ordinary Differential Equations** Ian Anderson, Gerard Thompson, 1992 This monograph explores various aspects of the inverse problem of the calculus of variations for systems of ordinary differential equations. The main problem centres on determining the existence and degree of generality of Lagrangians whose system of Euler-Lagrange equations coincides with a given system of ordinary differential equations. The authors rederive the basic necessary and sufficient conditions of Douglas for second order equations and extend them to equations of higher order using methods of the variational bicomplex of Tulczyjew, Vinogradov, and Tsujishita. The authors present an algorithm, based upon exterior differential systems techniques, for solving the inverse problem for second order equations. a number of new examples illustrate the effectiveness of this approach.

**calculus of variations: Calculus of Variations** Hansjörg Kielhöfer, 2018-01-25 This clear and concise textbook provides a rigorous introduction to the calculus of variations, depending on functions of one variable and their first derivatives. It is based on a translation of a German edition of the book *Variationsrechnung* (Vieweg+Teubner Verlag, 2010), translated and updated by the author himself. Topics include: the Euler-Lagrange equation for one-dimensional variational problems, with and without constraints, as well as an introduction to the direct methods. The book targets students who have a solid background in calculus and linear algebra, not necessarily in functional analysis. Some advanced mathematical tools, possibly not familiar to the reader, are given along with proofs in the appendix. Numerous figures, advanced problems and proofs, examples, and exercises with solutions accompany the book, making it suitable for self-study. The book will be particularly useful for beginning graduate students from the physical, engineering, and mathematical sciences with a rigorous theoretical background.

**calculus of variations: Optimal Control and the Calculus of Variations** Enid R. Pinch, 1995 A paperback edition of this successful textbook for final year undergraduate mathematicians and control engineering students, this book contains exercises and many worked examples, with complete solutions and hints making it ideal not only as a class textbook but also for individual study. The introduction to optimal control begins by considering the problem of minimizing a function of many variables, before moving on to the main subject: the optimal control of systems governed by ordinary differential equations.

**calculus of variations: A First Course in the Calculus of Variations** Mark Kot, 2014-10-06 This book is intended for a first course in the calculus of variations, at the senior or beginning graduate level. The reader will learn methods for finding functions that maximize or minimize integrals. The text lays out important necessary and sufficient conditions for extrema in historical order, and it illustrates these conditions with numerous worked-out examples from mechanics, optics, geometry, and other fields. The exposition starts with simple integrals containing a single independent variable, a single dependent variable, and a single derivative, subject to weak variations, but steadily moves on to more advanced topics, including multivariate problems, constrained extrema, homogeneous problems, problems with variable endpoints, broken extremals, strong variations, and sufficiency conditions. Numerous line drawings clarify the mathematics. Each chapter ends with recommended readings that introduce the student to the relevant scientific literature and with exercises that consolidate understanding.

**calculus of variations: Calculus of Variations and Optimal Control Theory** Daniel Liberzon, 2012-01-08 This textbook offers a concise yet rigorous introduction to calculus of variations and optimal control theory, and is a self-contained resource for graduate students in engineering, applied mathematics, and related subjects. Designed specifically for a one-semester course, the book begins with calculus of variations, preparing the ground for optimal control. It then gives a complete proof of the maximum principle and covers key topics such as the Hamilton-Jacobi-Bellman theory of

dynamic programming and linear-quadratic optimal control. Calculus of Variations and Optimal Control Theory also traces the historical development of the subject and features numerous exercises, notes and references at the end of each chapter, and suggestions for further study. Offers a concise yet rigorous introduction Requires limited background in control theory or advanced mathematics Provides a complete proof of the maximum principle Uses consistent notation in the exposition of classical and modern topics Traces the historical development of the subject Solutions manual (available only to teachers) Leading universities that have adopted this book include: University of Illinois at Urbana-Champaign ECE 553: Optimum Control Systems Georgia Institute of Technology ECE 6553: Optimal Control and Optimization University of Pennsylvania ESE 680: Optimal Control Theory University of Notre Dame EE 60565: Optimal Control

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**calculus of variations: Calculus of Variations** C. R. MacCluer, 2005 This is the first truly up-to-date treatment of calculus of variations - and the first to incorporate a simple introduction to key concepts such as optimization, optimal control, bang-bang, Pontryagin's maximum principle, or LQ control design. Introduces all material using simple, easily understood applications that are worked and reprised several times throughout. Features a large number of exercises, ranging widely in difficulty. Gives readers a broader, big picture perspective that makes the material less overwhelming. Offers a useful, stand-alone discussion of MATLAB (MATLAB Cookbook) in the appendices. Includes a clear introduction to weak/strong sufficiency. A useful reference for engineers, chemists, and forest/environmental managers.

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